



Quiz Questions

Dynamic Analysis using Ansys Workbench LS-DYNA Software

Developed and curated by the Ansys part of Synopsys Academic Program

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This resource mentions Ansys LS-DYNA® nonlinear dynamics structural simulation software and Ansys Workbench™ (WB) simulation integration platform.

Below is a series of questions to go along with the Fundamentals of Dynamic Analysis using Ansys Workbench LS-DYNA Software Part 1 Lecture.

1. What distinguishes structural dynamic analysis from static structural analysis?
 - A. It accounts for time-dependent loading and inertia effects
 - B. It only uses linear material models
 - C. It neglects damping
 - D. It ignores deformation

****Answer:** A**

2. In explicit dynamics, the solution is advanced:
 - A. Using Newton-Raphson iteration
 - B. Implicit time integration
 - C. Directly in time without solving a global stiffness matrix
 - D. By solving eigenvalue problems

****Answer:** C**

3. Which of the following best describes an appropriate application for Ansys LS-DYNA software in the Ansys Workbench platform?
 - A. High-speed impact simulation
 - B. Long-duration heat transfer
 - C. Static load on a beam
 - D. Steady-state fluid flow

****Answer:** A**

4. What is the key feature of the central difference time integration method used in explicit dynamics?
 - A. Implicit and unconditionally stable
 - B. Conditionally stable with small time steps
 - C. Requires matrix inversion at each step
 - D. Conditionally stable with large time steps

****Answer:** B**

5. What is the purpose of mass scaling in explicit analysis?
 - A. Reduce computational errors
 - B. Increase stable time step by artificially increasing mass
 - C. Increase mesh density
 - D. Reduce memory usage

****Answer:** B**

6. In a well-behaved explicit dynamics simulation, which of the following should remain approximately constant to indicate stability?

- A. Total Energy
- B. Internal Energy
- C. Hourglass Energy
- D. Kinetic Energy

****Answer:** A**

7. Hourglass control is used in Ansys LS-DYNA software to:

- A. Prevent spurious zero-energy deformation modes
- B. Increase simulation speed
- C. Reduce boundary conditions
- D. Scale mesh quality

****Answer:** A**

8. A high hourglass energy relative to internal energy may indicate:

- A. Model convergence
- B. Valid simulation results
- C. Instability or under-integrated element distortion
- D. Excessive damping

****Answer:** C**

9. In the Taylor impact test, what is primarily analyzed?

- A. Plastic deformation from high-speed impact
- B. Modal frequencies
- C. Structural buckling
- D. Thermal resistance

****Answer:** A**

10. Which of the following is not typically a reason for using explicit analysis over implicit?

- A. Modeling fast transients
- B. Large deformation problems
- C. Long-term creep analysis
- D. Contact-heavy simulations

****Answer:** C**

11. What is the primary objective of mass scaling in explicit analysis?

- A. To improve material damping behavior
- B. To increase the element stiffness
- C. To artificially raise the stable time step by increasing mass
- D. To reduce hourglass modes

****Answer:** C**

12. The critical time step in an explicit simulation is most strongly dependent on:

- A. Number of elements
- B. Young's modulus
- C. The smallest element length and wave speed (per CFL condition)
- D. Total simulation time

****Answer:** C**

13. According to the Courant-Friedrichs-Lewy (CFL) condition, which of the following helps increase the stable time step in an explicit simulation?

- A. Decreasing material stiffness
- B. Using smaller elements
- C. Increasing wave propagation speed
- D. Reducing density

****Answer:** A**

14. In an ideal explicit dynamic simulation with no energy loss, which of the following should remain approximately constant?

- A. Hourglass energy
- B. Kinetic energy
- C. Total energy (kinetic + internal + contact, etc.)
- D. Work done by boundary conditions

****Answer:** C**

15. A significant increase in hourglass energy during a simulation may indicate:

- A. The simulation is stable and accurate
- B. Excessive artificial stiffness
- C. Numerical instability and possible mesh distortion
- D. Improved accuracy from reduced integration

****Answer:** C**

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